Programming: C++, C, Python, JavaScript

Robotics: ROS, OpenCV, Manipulators, Networking

Perception: Kalman Filter, Particle Filter, Graph SLAM

Navigation: Path Planning, Controls, Obstacle Detection

Embedded: ARM, Raspberry Pi, Jetson, MCU, Motors

Sensors: LiDAR, Camera, IMU, GPS, UWB, Encoders, Arms

Tools: Git, Linux, Bash, Multithreading, Jenkins, JIRA

Web Dev: React, React Native, Node, Express, SQL

Languages and Technologies

Bachelor of Engineering, Mechatronics Engineering (Co-op)

McMaster University, Dean’s Honour List (3.8 GPA), Teaching Assistant

Education

Diligent Software Engineer possessing a Bachelor of Engineering and 3 years of working experience in software and simulation development, with emphasis in autonomous vehicle and mobile robot technologies. Passionate about building robust end-to-end software solutions that seamlessly interface hardware systems with humans and real-world applications.

Profile Summary

Employment

Software Developer July 2021 to Present

Clearpath Robotics, Platform OS

* Innovate and maintain open-source and proprietary software for ROS 1 and ROS 2 mobile robotic platforms.
* Develop internal software tools and test suites to support integration, client success, and production teams.
* Execute custom software integrations of sensors, manipulators, and networking devices with robots.
* Collaborate with cross-functional engineering teams and PMs to deliver on complex engineering projects.

Software Engineer January 2021 to June 2021

ARVI AI, Autonomous Driving

* Implemented and demoed localization, mapping, and autonomous navigation on a Polaris GEM electric vehicle.
* Developed middleware for reliable communication between hardware, software, and simulation systems.
* Wrote software drivers to integrate sensors, steering and throttle controllers with real vehicle, simulation, and ROS.

Software Developer Intern June 2020 to September 2020

Clearpath Robotics, Platform OS

* Spearheaded Node/Express backend development of a web application that allows remote user interface with ROS robots, including manual control and sending autonomous navigation missions via satellite map.
* Built intuitive frontend components using React to enhance user interface experience with the web application.

Simulation Engineer Intern May 2018 to August 2019

OTTO Motors, Simulation Services

* Designed and developed high-level Simio simulation models of autonomous mobile robots in customer’s facilities, to conceptualize and evaluate material transport solutions.
* Extended internal simulation software library with crucial features, such as key metric trackers for robot missions.

Personal Projects

Affordable Outdoor Localization, Research Capstone May 2020 to April 2021

* Led engineering design and implementation of an outdoor localization solution, which fuses low-cost IMU and UWB sensors using a Particle Filter in ROS to estimate robot pose.

Guardian, Intelligent Surveillance System April 2020 to July 2020

* Architected an intelligent surveillance system on a Raspberry Pi that leverages ROS, OpenCV, and live camera data to detect intruders, and alert users via text and email.

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Joey Yang

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